# Nonlinear Conservation Laws in Applied Sciences

#### 2017 Summer School in Nonlinear PDE Lecture 2

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#### ON A FLUIF-PARTICLE INTERACTION MODEL

#### OUTLINE:

- Modeling
- Energy Estimates
- Notion of Solutions
- Construction of approximate problems
- Main Results: Global-in-time Existence with Large Data
- Challenge: Pass into the limit. Compactness
- Methods: Div-Curl Lemma, Weak continuity of effective viscous pressure, Multipliers technique
- Consequences: Asymptotics, Singular limits

#### Fluid-Particle Interactions

Fluid-particle interactions arise in many practical applications: biotechnology, medicine, fuel droplets in combustion, sprays etc. Here, we focus on a particular system derived by formal **asymptotics** from a **mesoscopic description**. This is based on a kinetic equation for the particle distribution of **Fokker-Planck type** coupled to fluid equations.

The coupling between the kinetic and the fluid equations: **friction forces** that the fluid and the particles exert mutually.

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The cloud of particles is described by its distribution function  $f_{\varepsilon}(t, x, \xi)$  on phase space, which is the solution to the dimensionless **Vlasov-Fokker-Planck** equation

$$\bigg|\partial_t f_{\varepsilon} + \frac{1}{\sqrt{\varepsilon}} \Big( \xi \cdot \nabla_x f_{\varepsilon} - \nabla_x \Phi \cdot \nabla_{\xi} f_{\varepsilon} \Big) = \frac{1}{\varepsilon} \operatorname{div}_{\xi} \Big( \big( \xi - \sqrt{\varepsilon} u_{\varepsilon} \big) f + \nabla_{\xi} f_{\varepsilon} \Big).$$

The friction force is assumed to follow **Stokes law** and thus is proportional to the relative velocity vector, i.e., is proportional to the fluctuations of the microscopic velocity  $\xi \in \mathbb{R}^3$  around the fluid velocity field **u**.

The RHS of the moment equation in the Navier-Stokes system takes into account the action of the cloud of particles on the fluid through the **forcing term** 

$$F_{\varepsilon} = \int_{\mathbb{R}^3} \left( \frac{\xi}{\sqrt{\varepsilon}} - u_{\varepsilon}(t, x) \right) f(t, x, \xi) \, d\xi.$$

The density of the particles  $\eta_{\varepsilon}(t, x)$  is related to the probability distribution function  $f_{\varepsilon}(t, x, \xi)$  through the relation

$$\eta_{\varepsilon}(t,x) = \int_{\mathbb{R}^3} f_{\varepsilon}(t,x,\xi) \, d\xi.$$

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$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + {\operatorname{div}}_x(\varrho(\mathbf{u}\otimes\mathbf{u}) + 
abla_x(
ho(\varrho) + \eta) - \mu\Delta\mathbf{u} - \lambda
abla_x\,{\operatorname{div}}_x\,\mathbf{u}$$

$$= -(\eta + \beta \varrho) \nabla \Phi,$$

$$\partial_t \eta + \operatorname{div}(\eta(\mathbf{u} - \nabla \Phi)) - \Delta \eta = 0.$$

$$\varrho = \varrho(t, x) - \text{total mass density} \qquad t - \text{time, } x \in \Omega \subset \mathbb{R}^3$$
 $u = u(t, x) - \text{velocity field}$ 
 $\eta = \eta(t, x) - \text{the density of the particles}$ 

$$p(\varrho) = a \varrho^{\gamma} \qquad a > 0, \gamma > 1, \beta \neq 0$$

#### Φ external potential

$$\mu > 0, \ \lambda + rac{2}{3}\mu \ge 0$$
 viscosity parameters

 $\beta > 0$  if  $\Omega$  is unbounded



$$\mathbf{u}|_{\partial\Omega} = 
abla \eta \cdot \nu + \eta 
abla \Phi \cdot \nu = 0 \quad \text{on} \quad (0, T) imes \partial\Omega$$

with  $\nu$  denoting the outer normal vector to the boundary  $\partial \Omega$ .

# Initial Conditions

 $(\varrho_0, \mathbf{m}_0, \eta_0)$  such that

$$\begin{cases} \varrho(0,x) = \varrho_0 \in L^{\gamma}(\Omega) \cap L^1_+(\Omega), \\ (\varrho \mathbf{u})(0,x) = \mathbf{m}_0 \in L^{\frac{6}{5}}(\Omega) \cap L^1(\Omega), \\ \eta(0,x) = \eta_0 \in L^2(\Omega) \cap L^1_+(\Omega). \end{cases}$$

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$$E(\eta, \varrho, \mathbf{u})(t) :=$$

$$\int_{\Omega} \left[\frac{1}{2}\varrho(t)|\mathbf{u}(t)|^{2} + \frac{a}{\gamma - 1}\varrho^{\gamma}(t) + \overbrace{(\eta \log \eta)(t)}^{Entropy} + \overbrace{(\beta \varrho + \eta)(t)\Phi}^{Potential Energy}\right] dx$$

$$Kinetic Energy$$

At the formal level, the total energy can be viewed as a Lyapunov function satisfying the **energy inequality** 

$$\frac{dE}{dt} + \int_{\Omega} \left[ \mu |\nabla \mathbf{u}|^2 + \lambda |\operatorname{div} \mathbf{u}|^2 + |2\nabla \sqrt{\eta} + \sqrt{\eta} \nabla \Phi|^2 \right] dx \le 0.$$

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#### Confinement hypothesis

Given a domain  $\Omega \in C^{2,\nu}$ ,  $\nu > 0$ ,  $\Omega \subset \mathbb{R}^3$ , and given a bounded from below external potential  $\Phi : \Omega \longrightarrow \mathbb{R}^+_0$  satisfying  $\inf_{x \in \Omega} \Phi(x) = 0$  we will say that  $(\Omega, \Phi)$  verifies the confinement hypotheses **(HC)** for the two-phase flow system coupled with no-flux boundary conditions whenever:

- If Ω is bounded, Φ is bounded and Lipschitz continuous in Ω
   and the sub-level sets [Φ < k] are connected in Ω for any
   k > 0.
- If Ω is unbounded, we assume that Φ ∈ W<sup>1,∞</sup><sub>loc</sub>(Ω), β > 0, the sub-level sets [Φ < k] are connected in Ω for any k > 0,

$$e^{-\Phi/2} \in L^1(\Omega),$$

and

$$|\Delta \Phi(x)| \leq c_1 |
abla \Phi(x)| \leq c_2 \Phi(x), |x| > R > 0$$

# Examples

The confinement assumption **(HC)** has physical relevance in our setting as it is verified for several domains  $\Omega$  with  $\Phi$  being the gravitational potential. For instance,

**1** when 
$$\Omega = \{x \in \mathbb{R}^3 \mid (x_1, x_2) \in [a, b]^2, x_3 \in [0, H]\}$$
 and  $\Phi(x) = gx_3$ , where  $\beta = 1 - \frac{\varrho_F}{\rho_P}$ 

2 when

$$\begin{split} \Omega &= \{x \in \mathbb{R}^3 \mid (x_1, x_2) \in [a, b]^2, \, x_3 > 0\} \text{ and } \Phi(x) = g x_3, \\ \text{where } \beta &= 1 - \frac{\varrho_F}{\varrho_P} \text{ and } \varrho_F < \varrho_P. \end{split}$$

(a) when  $\Omega = \mathbb{R}^3 \setminus \overline{B(0, R)}$  and  $\Phi(x) = g|x|$ , where B(0, R) is the ball centered at the origin with radius R and  $\beta > 0$ .

Here,  $\varrho_F$  and  $\varrho_P$  are the typical mass density of fluid and particles, respectively. Remark that 1. corresponds to the standard bubbling case in which particles move upwards due to buoyancy.

#### Derivation of the model

Set up of the model: The particles are viewed as identical spheres of radius R > 0 with a uniform mass density. Assuming a friction force which is proportional to the velocity difference between the particles and the fluid, on a single particle, the fluid produces a frictional force of

$$F(t, x, \xi) = 6\pi\mu R[\mathbf{u}(t, x) - \xi]$$

where  $\mu$  is the dynamic viscosity of the fluid. Accordingly, the force exerted by the particles on the fluid is given by the sum

$$6\pi\mu R\int_{\mathbb{R}^3} [\mathbf{u}(t,x)-\xi] fd\xi.$$

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The particles move under the influence of Brownian motion, resulting in diffusion in  $\xi$ . Here the diffusion coefficient is given by

$$D = \frac{k\theta}{m_P} \frac{6\pi\mu R}{m_P} = \frac{k\theta}{m_P} \frac{9\mu}{2R^2\varrho_F}$$

where

- $\rho_P$  is the constant mass density of each particle,
- m<sub>P</sub> is the total mass of each particle,
- k is the Boltzmann constant, and
- $\theta$  is the constant temperature of the system.

# Remark.

Here

$$\mathcal{T}_{s} = \frac{m_{P}}{6\pi\mu R} = \frac{2R^{2}\varrho_{P}}{9\mu}$$

is the natural relaxation time for the kinetic equation usually referred in these applications as the **Stokes settling time**. We consider as usual

$$\mathcal{V}_{th} = \sqrt{rac{k heta}{m_P}}$$

as the measure of the *fluctuation of particles velocity*, called their **thermal speed**.

In light of this setup, the equations for the unknowns  $\varrho,\,{\bf u},$  and f read

$$\begin{cases} \partial_t \varrho + \operatorname{div}(\varrho \mathbf{u}) = 0 \\ \partial_t(\varrho \mathbf{u}) + \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\varrho) = -\beta \varrho \nabla \Phi + \frac{6\pi \mu R}{\varrho_F} \int_{\mathbb{R}^3} (\xi - \mathbf{u}) f \, \mathrm{d}\xi \\ \partial_t f + \xi \cdot \nabla f - \nabla \Phi \cdot \nabla_\xi f = \frac{9\mu}{2R^2 \varrho_P} \operatorname{div}_\xi \left[ (\xi - \mathbf{u}) f + \frac{k\theta}{m_P} \nabla_\xi f \right]. \end{cases}$$
(1)

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Taking unitless parameters and defining

$$\varepsilon = \frac{\mathcal{T}_s}{T}$$

the ratio of the Stokes settling time for microscopic diffusion (denoted  $T_s$ ) and the characteristic time (denoted T) we obtain:

$$\partial_t \varrho_{\varepsilon} + \operatorname{div}_x(\varrho_{\varepsilon} \mathbf{u}_{\varepsilon}) = 0$$
 (2)

$$\partial_{t}(\varrho_{\varepsilon}\mathbf{u}_{\varepsilon}) + \operatorname{div}_{x}(\varrho_{\varepsilon}\mathbf{u}_{\varepsilon}\otimes\mathbf{u}_{\varepsilon}) + \nabla_{x}(\rho(\varrho_{\varepsilon})) \tag{3}$$
$$= -\beta\varrho_{\varepsilon}\nabla_{x}\Phi + \int_{\mathbb{R}^{3}}\left(\frac{\xi}{\sqrt{\varepsilon}} - \mathbf{u}_{\varepsilon}\right)f_{\varepsilon}\mathrm{d}\xi$$
$$\partial_{t}f_{\varepsilon} + \frac{1}{\sqrt{\varepsilon}}(\xi\cdot\nabla_{x}f_{\varepsilon} + \nabla_{x}\Phi\cdot\nabla_{\xi}f_{\varepsilon}) = \frac{1}{\varepsilon}\operatorname{div}_{\xi}[(\xi - \sqrt{\varepsilon}\mathbf{u}_{\varepsilon})f_{\varepsilon} + \nabla_{\xi}f_{\varepsilon}]. \tag{4}$$

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In the mesoscopic model (2)-(4),  $\varrho_{\varepsilon}$  is the fluid density,  $\mathbf{u}_{\varepsilon}$  is the fluid velocity field, and  $f_{\varepsilon}$  is the mesoscopic particle density, the three of which are the unknowns. In light of Newton's Third Law, the quantity

$$\int_{\mathbb{R}^3} \left( \frac{\xi}{\sqrt{\varepsilon}} - \mathbf{u}_{\varepsilon} \right) f_{\varepsilon} \, \mathrm{d}\xi$$

represents the frictional force exerted by the particles on the fluid. The macroscopic particle density  $\eta_{\varepsilon}$  is related to the mesoscopic particle density  $f_{\varepsilon}$  by the relation

$$\eta_{\varepsilon}(x,t) = \int_{\mathbb{R}^3} f_{\varepsilon}(x,\xi,t) d\xi.$$
 (5)

To derive the NSS system from (2)-(4), the asymptotic limit  $\varepsilon \rightarrow 0$  is taken, representing that the **Stokes settling time** becomes **negligible** compared to the **characteristic time scale** under consideration. Indeed, following the formal analysis in Carrillo and Goudon (2006) and denoting the first and second moments of  $f_{\varepsilon}$  as

$$J_{arepsilon}(x,t) := \int_{\mathbb{R}^3} rac{1}{\sqrt{arepsilon}} \xi f_{arepsilon}(x,t,\xi) \; \mathrm{d} \xi$$

and

$$\mathbb{P}_{\varepsilon}(x,t) := \int_{\mathbb{R}^3} \xi \otimes \xi f_{\varepsilon}(x,t,\xi) \, \mathrm{d}\xi,$$

respectively, the following equations for the moments are obtained using (4):

$$\partial_t \eta_{\varepsilon} + \operatorname{div} J_{\varepsilon} = 0$$
 (6)

$$\varepsilon \partial_t J_{\varepsilon} + \operatorname{div} \mathbb{P}_{\varepsilon} + \eta_{\varepsilon} \nabla \Phi = -(J_{\varepsilon} - \eta_{\varepsilon} \mathbf{u}_{\varepsilon}).$$
(7)

Taking  $\varepsilon \to 0$  and integrating (7) over  $\mathbb{R}^3$  yields formally

$$\nabla \eta + \eta \nabla \Phi = -J + \eta \mathbf{u}. \tag{8}$$

Inserting this into (6) and taking the limit yields the Smoluchowski equation.

$$\partial_t \eta + \operatorname{div}(\eta(\mathbf{u} - \nabla \Phi)) - \Delta \eta = 0.$$



Variational Formulation

- Derivatives  $\sim$  in the sense of distributions
- Equations  $\sim$  family of integral identities

Approach

- collect all available a priori estimates
- construct a sequence of approximate problems whose solutions satisfy these estimate
- show that the sequence of approximate slns converges to solution of the original problem.

$$E(\eta, \varrho, \mathbf{u})(t) :=$$

$$\int_{\Omega} \left[\frac{1}{2}\varrho(t)|\mathbf{u}(t)|^{2} + \frac{a}{\gamma - 1}\varrho^{\gamma}(t) + \overbrace{(\eta \log \eta)(t)}^{Entropy} + \overbrace{(\beta \varrho + \eta)(t)\Phi}^{Potential Energy}\right] dx$$

$$Kinetic Energy$$

At the formal level, the total energy can be viewed as a Lyapunov function satisfying the **energy inequality** 

$$\frac{dE}{dt} + \int_{\Omega} \left[ \mu |\nabla \mathbf{u}|^2 + \lambda |\operatorname{div} \mathbf{u}|^2 + |2\nabla \sqrt{\eta} + \sqrt{\eta} \nabla \Phi|^2 \right] dx \le 0.$$

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#### How do we derive the energy inequality?

We compute the time derivative of each component in the energy.

$$\partial_t \left( rac{1}{2} arrho(t) |\mathbf{u}(t)|^2 
ight) = ?$$

Multiplying the momentum equation by **u**:

$$\frac{\partial}{\partial t} \left( \frac{1}{2} \varrho(t) |\mathbf{u}(t)|^2 \right) + \operatorname{div} \left( \frac{1}{2} \varrho(t) |\mathbf{u}(t)|^2 \mathbf{u} \right)$$

$$+\operatorname{div}(\varrho^{\gamma}\mathbf{u}) - \varrho^{\gamma}\operatorname{div}\mathbf{u} + \operatorname{div}(\eta\mathbf{u}) - \eta\operatorname{div}\mathbf{u} =$$
$$\mu\mathbf{u}\Delta\mathbf{u} + \lambda\mathbf{u}\nabla\operatorname{div}\mathbf{u} - (\eta + \beta\varrho)\mathbf{u}\nabla\Phi$$

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Multiplying the momentum equation by **u**:

$$\frac{\partial}{\partial t} \left( \frac{1}{2} \varrho(t) |\mathbf{u}(t)|^2 \right) + \operatorname{div} \left( \frac{1}{2} \varrho(t) |\mathbf{u}(t)^2 \mathbf{u} \right) + \frac{\mathbf{u}^2}{2} [\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u})]$$

$$+\operatorname{div}(\varrho^{\gamma}\mathbf{u}) - \varrho^{\gamma}\operatorname{div}\mathbf{u} + \operatorname{div}(\eta\mathbf{u}) - \eta\operatorname{div}\mathbf{u} =$$
$$\mu\mathbf{u}\Delta\mathbf{u} + \lambda\mathbf{u}\nabla\operatorname{div}\mathbf{u} - (\eta + \beta\varrho)\mathbf{u}\nabla\Phi$$

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$$\frac{\partial}{\partial t}\left(\beta(\varrho)\right) = ?$$

Multiplying the continuity equation by  $(\beta(\varrho))'$ :

(

$$\frac{\partial}{\partial t} (\beta(\varrho))) + \operatorname{div} (\beta(\varrho)\mathbf{u}) -? = 0$$
$$\operatorname{div} (\beta(\varrho)\mathbf{u}) = \beta'(\varrho)\nabla \varrho \,\mathbf{u} + \beta(\varrho)\operatorname{div} \mathbf{u}$$
$$\operatorname{div} (\beta(\varrho)\mathbf{u}) = \beta'(\varrho)\operatorname{div} (\varrho \mathbf{u}) - \beta'(\varrho)\varrho\operatorname{div} \mathbf{u} + \beta(\varrho)\operatorname{div} \mathbf{u}$$

$$\frac{\partial}{\partial t}(\beta(\varrho))) + \operatorname{div}(\beta(\varrho)\mathbf{u}) + \left[\beta'(\varrho)\varrho - \beta(\varrho)\right]\operatorname{div}\mathbf{u} = 0$$

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$$\frac{\partial}{\partial t} \left( \frac{a \varrho^{\gamma}}{\gamma - 1} \right) = ?$$

Multiplying the continuity equation by  $(\varrho^{\gamma})'$ :

$$rac{\partial}{\partial t}\left(arrho^{\gamma}
ight)+ ext{div}\left(arrho^{\gamma} extbf{u}
ight)+arrho^{\gamma}(\gamma-1)\, ext{div}\, extbf{u}=0$$

Indeed:

$$[\beta'(\varrho)\varrho - \beta(\varrho)] = \gamma \varrho^{\gamma-1} \varrho - \varrho^{\gamma} = (\gamma - 1)\varrho^{\gamma}$$

Dividing by  $(\gamma - 1)$ :

$$\boxed{\frac{\partial}{\partial t} \left(\frac{\varrho^{\gamma}}{\gamma - 1}\right) + \operatorname{div} \left(\frac{\varrho^{\gamma}}{\gamma - 1}\mathbf{u}\right) + \varrho^{\gamma} \operatorname{div} \mathbf{u} = 0}$$

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$$\partial_t \left( \eta \log \eta \right) = ?$$

Multiplying Smoluchowski equation by  $(\eta \log \eta)'$ :

 $\left| \frac{\partial}{\partial t} \left( \eta \log \eta \right) + \operatorname{div} \left( \eta \log \eta \mathbf{u} \right) + \eta \operatorname{div} \mathbf{u} = (\log \eta + 1) \Delta \eta \right|$ 

$$\frac{d}{dt}\left(\beta\varrho+\eta\right)(t)\Phi(x)=?$$

$$\frac{d}{dt}\left(\beta\varrho+\eta\right)\Phi=\operatorname{div}\left[-(\beta\varrho+\eta)\mathbf{u}\right]\Phi-\operatorname{div}(\eta\nabla\Phi)\Phi-\Delta\eta\Phi.$$

Adding the above relations, applying integration by parts and using the boundary conditions we obtain:

$$\begin{split} E(\varrho,\mathbf{u},\eta)(t) + \int_0^t \int_\Omega \Big[\mu |\nabla \mathbf{u}|^2 + \lambda |\operatorname{div} \mathbf{u}|^2 + |2\nabla \sqrt{\eta} + \sqrt{\eta} \nabla \Phi|^2 \Big] dx ds \\ = E(\varrho,\mathbf{u},\eta)(0). \end{split}$$

with

$$E(t) := \int_{\Omega} \left[ \frac{1}{2} \varrho |\mathbf{u}|^2 + \frac{a}{\gamma - 1} \varrho^{\gamma} + (\eta \log \eta) + (\beta \varrho + \eta) \Phi \right] dx$$

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It is reasonable to anticipate that, at least for some sequences  $t_n \to \infty$ ,

$$\eta(t_n) \to \eta_s, \ \varrho(t_n) \to \varrho_s, \ \varrho \mathbf{u}(t_n) \to 0$$

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where  $\eta_s, \varrho_s$  satisfy the stationary problem

$$abla(
ho(arrho_s)+\eta_s)=-(\eta_s+etaarrho_s)
abla \Phi$$
 on  $\Omega$ 

The energy estimate written in the form

$$E(t) + \int_0^T (\|\nabla \mathbf{u}\|_{L^2}^2 + \|\operatorname{div} \mathbf{u}\|_{L^2}^2) dt + \int_0^T \int_\Omega |2\nabla \sqrt{\eta} + \sqrt{\eta} \nabla \Phi|^2 dt$$
$$\leq E(0)$$

$$|2\nabla\sqrt{\eta_s} + \sqrt{\eta_s}\nabla\Phi|^2 = 0$$

The aim of this paper is to show that, in fact, any weak solution converges to a fixed stationary state as time goes to infinity, more precisely,

$$\begin{split} \varrho(t) &
ightarrow arrho_{s} & ext{strongly in} & L^{\gamma}(\Omega), \\ & ext{ess}\sup_{\tau > t} \int_{\Omega} \varrho(\tau) |\mathbf{u}(\tau)|^{2} 
ightarrow \mathbf{0}, \\ & \eta(t) &
ightarrow \eta_{s} & ext{strongly in} & L^{p}(\Omega), \end{split}$$

as  $t \to \infty$  under the **confinement hypothesis** on the domain  $\Omega$ .

The steady state  $(\rho_s, \eta_s)$  are determined by

$$\begin{cases} \nabla p(\varrho_s) = -\beta \varrho_s \nabla \Phi, & \int_{\Omega} (\varrho_s, \eta_s) \, dx = \int_{\Omega} (\varrho_0, \eta_0) \, dx, \\ \nabla \eta_s = -\eta_s \nabla \Phi, & \int_{\Omega} (\varrho_s, \eta_s) \, dx = \int_{\Omega} (\varrho_0, \eta_0) \, dx, \end{cases}$$

and are given by the formulas

$$\varrho_{s} = \left(\frac{\gamma - 1}{a\gamma}\left[-\beta\Phi + C_{\varrho}\right]^{+}\right)^{\frac{1}{\gamma - 1}} \qquad \eta_{s} = C_{\eta}\exp(-\Phi),$$

where  $C_{\eta}$  and  $C_{\varrho}$  are uniquely given by the initial masses.

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# How do we find the appropriate space setting?

Assume smooth solutions. By integrating the continuity equation in space and time:

Bound of Energy implies:

$$\begin{split} \varrho \in L^{\infty}([0, T]; L^{\gamma}(\Omega)) \\ \frac{1}{2} \varrho |\mathbf{u}|^{2} \in L^{\infty}([0, T]; L^{1}(\Omega)) \Rightarrow \sqrt{\varrho} |\mathbf{u}| \in L^{\infty}([0, T]; L^{2}(\Omega)) \\ \varrho \mathbf{u} \in L^{\infty}([0, T]; L^{\frac{2\gamma}{\gamma+1}}(\Omega; \mathbb{R}^{3}) \end{split}$$

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# Bound of Energy implies (cont.):

$$\begin{split} \textbf{u} \in L^2(0,\,\mathcal{T};\, W^{1,2}_0(\Omega;\,\mathbb{R}^3)) \\ \Downarrow \end{split}$$

 $\boldsymbol{u}$  satisfy the boundary condition in the sense of traces

$$\eta \log \eta \in L^{\infty}([0, T]; L^{1}(\Omega))$$
  
 $\eta \in L^{2}([0, T]; L^{3/2}(\Omega)) \cap L^{1}(0, T; W^{1, \frac{3}{2}}(\Omega))$ 

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The energy inequality yields

$$2\nabla_x\sqrt{\eta}+\sqrt{n}\nabla_x\Phi\in L^2(0,\,T;\,L^2(\Omega;\,\mathbb{R}^3)).$$

Since  $\eta \in L^{\infty}(0, T; L^{1}(\Omega))$  and  $\nabla_{x} \Phi$  is uniformly bounded

$$\downarrow$$
 $abla_x \sqrt{\eta} \in L^2(0, T; L^2(\Omega; \mathbb{R}^3)),$ 

and so

$$\sqrt{\eta} \in L^2(0, T; W^{1,2}(\Omega)) \hookrightarrow L^2(0, T; L^6(\Omega)).$$

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Using these estimates, the quantity

$$\nabla_{\mathsf{x}}\eta=2\sqrt{\eta}\nabla_{\mathsf{x}}\sqrt{\eta},$$

and Hölder's inequality the particle density  $\eta$  satisfies

$$\eta \in L^1(0, T; W^{1,3/2}(\Omega)) \hookrightarrow L^1(0, T; L^3(\Omega)),$$
$$\eta \in L^2(0, T; W^{1,1}(\Omega)) \hookrightarrow L^2(0, T; L^{3/2}(\Omega)).$$

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$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$
  
$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho(\mathbf{u} \otimes \mathbf{u}) + \nabla_x(\rho(\varrho) + \eta) - \mu \Delta \mathbf{u} - \lambda \nabla_x \operatorname{div}_x \mathbf{u}$$
  
$$= -(\eta + \beta \varrho) \nabla \Phi,$$
  
$$\partial_t \eta + \operatorname{div}(\eta(\mathbf{u} - \nabla \Phi)) - \Delta \eta = 0.$$



$$\mathbf{u}|_{\partial\Omega} = \nabla \eta \cdot \nu + \eta \nabla \Phi \cdot \nu = 0 \text{ on } (0, T) \times \partial \Omega$$

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Strategy



Variational Formulation

- Derivatives  $\sim$  in the sense of distributions
- Equations  $\sim$  family of integral identities

Approach

- collect all available a priori estimates
- construct a sequence of approximate problems whose solutions satisfy these estimate
- show that the sequence of approximate slns converges to solution of the original problem.

# Weak solutions

The idea of weak solutions is based on the concept of *generalized derivatives* or distibutions. Classical functions are replaced by *integral averages* 

$$f: Q \to R \approx \int_Q f \varphi, \ \varphi \in C^\infty_c(Q).$$

 $C_c^{\infty}(Q)$  denotes the set of infinitely differentiable functions with compact support in Q.

Differential operators D can be conveniently expressed by means of a formal by-parts integration:

$$Df \approx -\int_{Q} f D\varphi, \ \varphi \in C^{\infty}_{c}(Q).$$

 $\parallel$ 

Any (localy) integrable function possesses derivatives of arbitrary order!

# **Renormalized solutions**

Multiplying the continuity equation by  $(B'(\varrho))$ :

$$\frac{\partial}{\partial t} \left( B(\varrho) \right) + \operatorname{div} \left( B(\varrho) \mathbf{u} \right) + b(\varrho) \operatorname{div}_{\mathsf{x}} \mathbf{u} = 0 \tag{9}$$

where

$$b(z) = B'(z)z - B(z)$$
 (10)

#### Definition

We say that  $\rho$  and **u** is a renormalized solution of the continuity equation on  $(0, T) \times \Omega$  if (9) holds in  $\mathcal{D}'((0, T) \times \Omega)$  for any functions

$$B\in {\mathcal C}[0,\infty)\cap {\mathcal C}^1(0,\infty),\,b\in {\mathcal C}[0,\infty)$$
 bounded on  $[0,\infty),$ 

B(0)=b(0)-0

satisfying (9)-(10) for all z > 0.

#### Free energy solutions

 $\{\varrho, \mathbf{u}, \eta\}$  is an admissible free energy solution of Problem D, supplemented with the initial data  $\{\varrho_0, \mathbf{u}_0, \eta_0\}$  provided that

*Q* ≥ 0, **u** is a **renormalized** solution of the continuity equation, that is,

$$\int_0^T \int_\Omega \left( \varrho B(\varrho) \partial_t \varphi + \varrho B(\varrho) \mathbf{u} \cdot \nabla_x \varphi - b(\varrho) \operatorname{div} \mathbf{u} \varphi \right) dx dt$$
$$= -\int_\Omega \varrho_0 B(\varrho_0) \varphi(0, \cdot) dx$$

holds for any test function  $\varphi \in \mathcal{D}([0, T) \times \overline{\Omega})$  and suitable *b* and *B*.

The balance of momentum holds in distributional sense. The velocity field **u** belongs to the space L<sup>2</sup>(0, T; W<sup>1,2</sup>(Ω; R<sup>3</sup>)), therefore it is legitimate to require **u** to satisfy the boundary conditions in the sense of traces.

Lecture 2: Notion of weak solutions

•  $\eta \geq 0$  is a weak solution of the Smoluchowski equation. That is,

$$\int_{0}^{\infty} \int_{\Omega} \eta \partial_{t} \varphi + \eta \mathbf{u} \cdot \nabla \varphi - \eta \nabla \Phi \cdot \nabla \varphi - \nabla \eta \nabla \varphi dx dt$$
$$= -\int_{\Omega} \eta_{0} \varphi(0, \cdot) dx$$

is satisfied for test functions  $\varphi \in \mathcal{D}([0, T) \times \overline{\Omega})$  and any T > 0. In particular,

$$\eta \in L^2([0, T]; L^{3/2}(\Omega)) \cap L^1(0, T; W^{1, \frac{3}{2}}(\Omega))$$

Lecture 2: Notion of weak solutions

• Given the total free-energy of the system by

$$\mathsf{E}(arrho, \mathbf{u}, \eta)(t) := \int_\Omega igg(rac{1}{2}arrho |\mathbf{u}|^2 + rac{a}{\gamma-1}arrho^\gamma + \eta\log\eta + (etaarrho + \eta) \Phiigg),$$

then  $E(\varrho, \mathbf{u}, \eta)(t)$  is finite and bounded by the initial energy of the system

$$E(arrho,\mathbf{u},\eta)(t)\leq E(arrho_0,\mathbf{u}_0,\eta_0)$$
 a.e.  $t>0$ 

Moreover, the following free energy-dissipation inequality holds

$$\begin{split} \int_0^\infty & \int_\Omega \left( \mu |\nabla \mathbf{u}|^2 + \lambda |\operatorname{div} \mathbf{u}|^2 + |2\nabla \sqrt{\eta} + \sqrt{\eta} \nabla \Phi|^2 \right) \, dt \\ & \leq E(\varrho_0, \mathbf{u}_0, \eta_0) \end{split}$$

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#### Theorem

Let  $\Omega \subset \mathbb{R}^3$  bounded domain and  $(\Omega, \Phi)$  satisfy the confinement hypotheses **(HC)**. Then, **Problem D** admits a weak solution  $\{\varrho, \mathbf{u}, \eta\}$  on  $(0, \infty) \times \Omega$ . In addition,

i) the total fluid mass and particle mass given by

$$M_arrho(t) = \int_\Omega arrho(t,\cdot) \; dx \qquad ext{and} \qquad M_\eta(t) = \int_\Omega \eta(t,\cdot) \; dx,$$

respectively, are constants of motion.

ii) the density satisfies the higher integrability result

 $\varrho \in L^{\gamma+\Theta}((0, T) \times \Omega)$ , for any T > 0,

where  $\Theta = \min\{\frac{2}{3}\gamma - 1, \frac{1}{4}\}.$ 

#### Theorem

Let us assume that  $(\Omega, \Phi)$  satisfy the confinement hypotheses **(HC)**. Then, for any free-energy solution  $(\varrho, \mathbf{u}, \eta)$  of the **Problem D**, there exist universal stationary states  $\varrho_s(x)$ ,  $\eta_s(x)$ , such that

$$\left\{ egin{array}{ll} arrho(t) 
ightarrow arrho_s \ ext{ strongly in } L^\gamma(\Omega), \ & \displaystyle ext{ ess sup } \int_\Omega arrho( au) | \mathbf{u}( au) |^2 \ dx 
ightarrow 0, \ & \displaystyle \eta(t) 
ightarrow \eta_s \ & \displaystyle ext{ strongly in } L^{p_2}(\Omega) \ & \displaystyle ext{for } p_2 > 1, \end{array} 
ight.$$

as  $t \to \infty$ , where  $(\eta_s, \varrho_s)$  are characterized as the unique free-energy solution of the stationary state problem:

Lecture 2: Main results

$$\begin{cases} \nabla p(\varrho_s) = -\beta \varrho_s \nabla \Phi, & \int_{\Omega} (\varrho_s, \eta_s) \, dx = \int_{\Omega} (\varrho_0, \eta_0) \, dx, \\ \nabla \eta_s = -\eta_s \nabla \Phi, & \int_{\Omega} (\varrho_s, \eta_s) \, dx = \int_{\Omega} (\varrho_0, \eta_0) \, dx, \end{cases}$$

given by the formulas

$$\varrho_s = \left(\frac{\gamma - 1}{a\gamma} \left[-\beta \Phi + C_{\varrho}\right]^+\right)^{\frac{1}{\gamma - 1}} \qquad \eta_s = C_{\eta} \exp(-\Phi),$$

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where  $C_{\eta}$  and  $C_{\varrho}$  are uniquely given by the initial masses.

# **Remark:**

We need to show that the sequences  $(\rho_n, \eta_n)$  of the time shifts defined as

$$\begin{split} \varrho_n(t,x) &:= \varrho(t+\tau_n,x), \ \tau_n \to \infty, \\ \eta_n(t,x) &:= \eta(t+\tau_n,x), \ \tau_n \to \infty, \end{split}$$

contain subsequences, denoted by the same index w.l.o.g., such that

$$arrho_{m{n}} o arrho_{m{s}} \hspace{0.5cm} ext{strongly in} \hspace{0.5cm} L^1_{loc}((0,1) imes \Omega)$$

and

 $\eta_n \to \eta_s$  strongly in  $L^{p_1}((0, T); L^{p_2})(\Omega)$  for some  $p_1, p_2 > 1$ ,

#### How do we construct suitable approximating problems?

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# An approximation scheme based on time-descretization

Reference: Carrillo, Karper, Trivisa, Nonlinear Analysis (2011)

Let  $\delta > 0$  be fixed. Given a time step h > 0, we discretize the time interval [0, T] in terms of the points  $t^k = kh$ , k = 0, ..., M, with Mh = T. Now, we sequentially determine functions

$$\{\varrho_{\delta,h}^k, \mathbf{u}_{\delta,h}^k, \eta_{\delta,h}^k\} \in \mathcal{W}(\Omega), \quad k = 1, \dots, M,$$

such that:

• The time discretized continuity equation,

$$d_t^h[\varrho_{\delta,h}^k] + \operatorname{div}(\varrho_{\delta,h}^k \mathbf{u}_{\delta,h}^k) = 0,$$

holds in the sense of distributions on  $\overline{\Omega}$ .

The time discretized momentum equation with artificial pressure,

$$\begin{aligned} d_t^h[\varrho_{\delta,h}^k \mathbf{u}_{\delta,h}^k] + \operatorname{div}(\varrho_{\delta,h}^k \mathbf{u}_{\delta,h}^k \otimes \mathbf{u}_{\delta,h}^k) - \mu \Delta \mathbf{u}_{\delta,h}^k - \lambda \nabla \operatorname{div} \mathbf{u}_{\delta,h}^k \\ + \nabla \left( p_{\delta}(\varrho_{\delta,h}^k) + \eta_{\delta,h}^k \right) &= -(\beta \varrho_{\delta,h}^k + \eta_{\delta,h}^k) \nabla \Phi \end{aligned}$$

holds in the sense of distributions on  $\boldsymbol{\Omega}$ 

• The time discretized particle density equation,

$$d_t^h[\eta_{\delta,h}^k] + \operatorname{div}\left(\eta_{\delta,h}^k(\mathbf{u}_{\delta,h}^k - \nabla\Phi)\right) - \Delta\eta_{\delta,h}^k = 0,$$

holds in the sense of distributions on  $\overline{\Omega}$ .

In the above equations,  $d_t^h[\phi^k] = \frac{\phi^k - \phi^{k-1}}{h}$  denotes implicit time stepping.

• There exists an artificial pressure solution  $(h \rightarrow 0)$ .

• Vanishing artificial pressure limit ( $\delta \rightarrow 0$ ).

#### An approximating scheme with the aid of Faedo-Galerkin approximations

Here the aproximate solutions are constructed using a three-level approximation scheme. Let  $X_n$  for  $n \in \mathbb{N}$  denote a family of finite dimensional spaces consisting of smooth vector-valued functions on  $\overline{\Omega}$  vanishing of  $\partial\Omega$ .

Two different types of regularizations are introduced:

- The ε-regularizations are included to guarantee that certain a priori estimates hold true while the energy inequality remains valid at each level of the approximation.
- **2** The  $\delta$ -regularization introduces an artificial pressure which is essential in obtaining the convergence result.

Thus, we consider the approximate system:

$$\partial_t \varrho_n + \operatorname{div}(\varrho_n \mathbf{u}_n) = \varepsilon \Delta \varrho_n$$
$$\partial_t \eta_n + \operatorname{div}(\eta_n(\mathbf{u}_n - \nabla \Phi)) = \Delta \eta_n$$
$$\int_{\Omega} \partial_t(\varrho_n \mathbf{u}_n) \cdot \mathbf{w} \, dx = \int_{\Omega} \varrho_n \mathbf{u}_n \otimes \mathbf{u}_n : \nabla \mathbf{w} + (a\varrho_n^{\gamma} + \eta_n + \delta \varrho_n^{\alpha}) \operatorname{div} \mathbf{w} \, dx$$
$$- \int_{\Omega} \mathbb{S}(\nabla \mathbf{u}) : \nabla \mathbf{w} + \varepsilon \nabla \varrho_n \cdot \nabla \mathbf{u}_n \cdot \mathbf{w} \, dx - \int_{\Omega} (\eta_n \varrho_n + \eta_n) \nabla \Phi \cdot \mathbf{w} \, dx$$

for any  $\mathbf{w} \in X_n$ , where  $X_n$  is a finite dimensional space and  $\alpha$  is suitably large exponent.

#### **Boundary conditions**

$$\nabla_{x} \varrho \cdot \mathbf{n} = 0, \ \mathbf{u}_{n} = (\nabla_{x} \eta_{n} + \eta_{n} \nabla_{x} \Phi) \cdot \mathbf{n} = 0 \text{ on } (0, T) \times \partial \Omega$$

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Here,  $\varepsilon, \delta > 0$  are small and  $\alpha$  is an appropriate constant. The approximation scheme is also supplemented by the approximate initial data  $\{\varrho_{0,\delta}, \mathbf{m}_{0,\delta}, \eta_{0,\delta}\}$ . The approximate initial data are modifications of the original initial data in that

- $0 < \delta \leq \varrho_{0,\delta} \leq \delta^{-1/2\alpha}$  for all  $x \in \Omega$ ,  $\varrho_{0,\delta} \to \varrho_0$  in  $L^{\gamma}(\Omega)$ , and  $|\{x \in \Omega | \varrho_{0,\delta}(x) < \varrho_0(x)\}| \to 0$  as  $\delta \to 0$ .
- $\mathbf{m}_{0,\delta}(x)$  is the same as  $\mathbf{m}_0(x)$  unless  $\varrho_{0,\delta}(x) < \varrho_0(x)$ , in which case  $\mathbf{m}_{0,\delta}(x) = 0$ .

•  $0 < \delta \leq \eta_{0,\delta} \leq \delta^{-1/2\alpha}$  for all  $x \in \Omega$ ,  $\eta_{0,\delta} \to \eta_0$  in  $L^2(\Omega)$ , and  $|\{x \in \Omega | \eta_{0,\delta}(x) < \eta_0(x)\}| \to 0$  as  $\delta \to 0$ .

# Motivation

The approximating system is motivated as follows.

- The continuity equation contains the additional Laplacian term εΔρ, known as vanishing viscosity, in order to increase the regularity of the density ρ and obtain strong compactness of the density at the first level of the approximation.
- In order to keep the energy estimate satisfied, the ε∇<sub>x</sub>u∇<sub>x</sub>ρ term in the modified momentum equation is introduced to balance the vanishing viscosity term.
- Finally, the δ<sub>ℓ</sub><sup>α</sup> term in the momentum equation serves to increase the integrability of the pressure during the first two levels of approximation. This is called the artificial pressure.

Here,  $\varepsilon, \delta > 0$  are small and  $\alpha$  is an appropriate constant. The approximation scheme is also supplemented by the approximate initial data  $\{\varrho_{0,\delta}, \mathbf{m}_{0,\delta}, \eta_{0,\delta}\}$ . The approximate initial data are modifications of the original initial data in that

- $0 < \delta \leq \varrho_{0,\delta} \leq \delta^{-1/2\alpha}$  for all  $x \in \Omega$ ,  $\varrho_{0,\delta} \to \varrho_0$  in  $L^{\gamma}(\Omega)$ , and  $|\{x \in \Omega | \varrho_{0,\delta}(x) < \varrho_0(x)\}| \to 0$  as  $\delta \to 0$ .
- $\mathbf{m}_{0,\delta}(x)$  is the same as  $\mathbf{m}_0(x)$  unless  $\varrho_{0,\delta}(x) < \varrho_0(x)$ , in which case  $\mathbf{m}_{0,\delta}(x) = 0$ .

•  $0 < \delta \leq \eta_{0,\delta} \leq \delta^{-1/2\alpha}$  for all  $x \in \Omega$ ,  $\eta_{0,\delta} \to \eta_0$  in  $L^2(\Omega)$ , and  $|\{x \in \Omega | \eta_{0,\delta}(x) < \eta_0(x)\}| \to 0$  as  $\delta \to 0$ .

#### In part, these hypotheses ensure that the initial energy

$$E(0) = E_{\delta}(0) :=$$

$$\int_{\Omega} \left( \frac{1}{2} \frac{|\mathbf{m}_{\mathbf{0},\delta}|^2}{\varrho_0} + \frac{\delta}{\alpha - 1} \varrho_{\mathbf{0},\delta}^{\alpha} + \eta_{\mathbf{0},\delta} \log \eta_{\mathbf{0},\delta} + (\beta \varrho_{\mathbf{0},\delta} + \eta_{\mathbf{0},\delta}) \Phi \right) dx,$$
  
is finite.

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# Faedo-Galerkin method

The (approximate) initial boundary value problem will be solved via a modified **Faedo-Galerkin method**. We start by introducing a finite-dimensional space

$$X_n = \operatorname{span} \{\pi_j\}_{j=1}^n, \qquad n \in \{1, 2, \dots\}$$

with  $\pi_j \in \mathcal{D}(\Omega)^N$  being a set of linearly independent functions which are dense in  $C_0^1(\bar{\Omega}, \mathbb{R}^N)$ .

The approximate velocities  $\mathbf{u}_n \in C([0, T]; X_n)$  satisfy a set of integral equations of the form

$$\int_{\Omega} \rho \mathbf{u}_{n}(\tau) \cdot \pi \, d\mathbf{x} - \int_{\Omega} \mathbf{m}_{0,\delta} \cdot \pi =$$
$$\int_{0}^{\tau} \int_{\Omega} (\rho \mathbf{u}_{n} \otimes \mathbf{u}_{n} - \mathbb{S}_{n}) : \nabla \eta + (p(\rho) + \eta + \delta \rho^{\beta}) \operatorname{div} \pi \, d\mathbf{x} dt$$
$$\int_{0}^{\tau} \int_{\Omega} (\varepsilon \nabla \mathbf{u}_{n} \nabla \rho) \cdot \pi \, d\mathbf{x} dt,$$

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for any test function  $\pi \in X_n$ , all  $\tau \in [0, T]$ .

#### The goal is to seek a fixed point

$$\mathbf{u}_n \in C([0, T]; X_n).$$

In order to carry this out, we need information on the mappings assigning each  $\mathbf{u}_n$  to unique solutions  $\varrho, \eta$  via the approximate continuity and Smoluchowski equations.

# **Existence for** $\varrho[u_n]$ .

**Proposition.** Let  $\Omega \subset \mathbb{R}^N$  be a bounded domain of class  $C^{2+\nu}$ ,  $0 < \nu \leq 1$ . Suppose that  $\varrho_{0,\delta} \in C^{2+\nu}(\bar{\Omega})$  is positive, and satisfies the condition

$$\nabla_{\mathbf{x}}\varrho_{\mathbf{0},\delta}\cdot\mathbf{n}=0$$
 on  $\partial\Omega$ .

Let  $\mathbf{u} \to \varrho[\mathbf{u}]$  assign to any  $\mathbf{u} \in C([0, T]; C_0^2(\bar{\Omega}; \mathbb{R}^3))$  a unique solution  $\varrho$  of the modified fluid density equation. Then this map takes **bounded sets** in the space  $C([0, T]; C_0^2(\bar{\Omega}; \mathbb{R}^3))$ , into **bounded sets** of the space

$$\mathcal{V} := \left\{ egin{array}{l} \partial_t arrho \in \mathcal{C}([0,T];\mathcal{C}^
u(ar\Omega)) \ arrho \in \mathcal{C}([0,T];\mathcal{C}^{2+
u}(ar\Omega)) \end{array} 
ight.$$

and the map  $\mathbf{u} \in C([0, T]; C_0^2(\overline{\Omega}; \mathbb{R}^3)) \to \varrho[\mathbf{u}] \in C^1([0, T] \times \overline{\Omega})$  is continuous.

# **Proposition.**

Let  $\Omega \subset \mathbb{R}^N$  be a bounded domain of class  $C^{2+\nu}, \nu > 0$ .

Then for any ρ<sub>0,δ</sub> and **u** ∈ C([0, T]; C<sub>0</sub><sup>ν</sup>(Ω
)) there is at most one weak solution ρ ∈ L<sup>2</sup>(0, T; W<sup>1,2</sup>(Ω)) of the approximate problem.

If, in addition,  $\rho_{0,\delta}$  belongs to  $C^{2+\nu}(\bar{\Omega})$  and satisfies the **(BC)**, then the approximate problem admits a unique classical solution  $\rho$ ,

$$arrho\in C([0,\,T];\,\mathcal{C}^{2+
u}(ar\Omega))\cap C^1([0,\,T];\,\mathcal{C}^
u(ar\Omega)).$$

#### Furthermore,

$$(\inf_{\Omega} \varrho_{0,\delta}) \exp\left(-\int_{0}^{\tau} \|\operatorname{div} \mathbf{u}_{n}(t)\|_{L^{\infty}} dt\right)$$
  

$$\leq \varrho(\tau, x) \leq$$

$$(\sup_{\Omega} \varrho_{0,\delta}) \exp\left(-\int_{0}^{\tau} \|\operatorname{div} \mathbf{u}_{n}(t)\|_{L^{\infty}} dt\right)$$

$$(11)$$

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for any  $\tau \geq 0$  and any  $x \in \Omega$ .

• The mapping  $\mathbf{u} \rightarrow \varrho[\mathbf{u}]$ ,

$$\varrho: C([0,T]; C_0^2(\bar{\Omega}; \mathbb{R}^N)) \to C([0,T]; C^{2+\nu}(\bar{\Omega}))$$

maps **bounded sets** in  $C([0, T]; C_0^2(\overline{\Omega}; \mathbb{R}^N))$  into **bounded** sets in

$$C([0, T]; C^{2+
u}(\bar{\Omega})) \cap C^1([0, T]; C^{
u}(\bar{\Omega}))$$

and has the property

$$\begin{split} \|\varrho(\mathbf{u}^{1}) - \varrho(\mathbf{u}^{2})\|_{\mathcal{C}([0,T];W^{1,2}(\Omega))} &\leq T \, c(r,T) \|\mathbf{u}^{1} - \mathbf{u}^{2}\|_{\mathcal{C}([0,T];W^{1,2}_{0}(\Omega))}, \\ \text{for any } \mathbf{u}^{1}, \mathbf{u}^{2} \text{ belonging to the set} \\ M_{r} &= \{\mathbf{u} \in \mathcal{C}([0,T];W^{1,2}_{0}(\Omega)) \,|\, \|\mathbf{u}(t)\|_{L^{\infty}(\Omega)} + \|\nabla \mathbf{u}(t)\|_{L^{\infty}} \leq r, \,\forall t\}. \end{split}$$

# **Existence of** $\eta[\mathbf{u}_n]$

**Proposition.** Let  $\Omega \subset \mathbb{R}^3$  be a bounded domain of class  $C^{2,\nu}, 0 < \nu \leq 1$ . Assume that  $\eta_{0,\delta} \in C^{0,\nu}(\bar{\Omega})$ , and  $\mathbf{u} \in C([0, T]; C_0^2(\bar{\Omega}; \mathbb{R}^3))$ . Let the compatibility condition

$$(\nabla_{x}\eta_{0,\delta}(\mathbf{x})+\eta_{0,\delta}(x)\nabla\Phi(x))\cdot\mathbf{n}(\mathbf{x})=0, \ \mathbf{x}\in\partial\Omega$$

be satisfied. Then the Smoluchowski equation has a unique classical solution  $\eta$  such that  $\eta \in V$ . The solution operator  $\mathbf{u} \to \eta[\mathbf{u}]$  assigning to any  $\mathbf{u} \in C([0, T]; C_0^2(\bar{\Omega}); \mathbb{R}^3)$  the unique solution of Smoluchowski equation takes **bounded sets** of  $C([0, T]; C_0^2(\bar{\Omega}; \mathbb{R}^3))$  into **bounded sets** in V.

# Existence of u<sub>n</sub>

It is now time to establish the local existence of a solution  $\mathbf{u}_n$  on a short interval [0, T(n)] for any fixed  $n \in \{1, 2, ...\}$ . Here, we express

$$\mathbf{u}_n(\tau) = \mathcal{M}^{-1}[\varrho(t)] \left( \mathbf{m}_{0,\delta}^* + \int_0^\tau \mathcal{N}[\mathbf{u}_n(t), \varrho(t), \eta(t)] dt \right).$$

Now,

$$\mathcal{M}[\varrho]: X_n \to X_n^*, \qquad \mathcal{N}[\varrho]: X_n \to X_n^*$$

are two operators defined by

$$<\mathcal{M}[\varrho]\mathbf{v},\mathbf{w}>=\int_{\Omega}arrho\pi\cdot\mathbf{w}\,dx,$$

$$<\mathcal{N}[\mathbf{u}_{n},\varrho,\eta],\pi>=\int_{\Omega}[\varrho\mathbf{u}_{n}\otimes\mathbf{u}_{n}-\mathbb{S}]:\nabla\pi+[p(\varrho)+\eta+\delta\varrho^{\alpha}]div\pi\,dx\\-\int_{\Omega}[\varepsilon\nabla\mathbf{u}_{n}\nabla\varrho+(\beta\varrho+\eta)\nabla_{x}\Phi]\cdot\pi dx,$$

respectively, with  $\varrho = \varrho[\mathbf{u}_n]$ ,  $\eta = \eta[\mathbf{u}_n]$ , while  $X_n^*$  denotes the dual space of the finite dimensional space  $X_n$  and  $\mathbf{m}^* \in X_n^*$  is given by

$$<\mathbf{m}^*_{\mathbf{0},\delta},\pi>=\int_{\Omega}\mathbf{m}_{\mathbf{0},\delta}\cdot\pi\,dx$$
 for  $\pi\in X_n.$ 

Next, observe that the Propositions above now yield that

$$\mathcal{T}[\mathbf{u}] = \mathcal{M}^{-1}[\varrho(t)] \left( \mathbf{m}_{0,\delta}^* + \int_0^\tau \mathcal{N}[\mathbf{u}(t), \varrho(t), \vartheta(t)] \, dt \right)$$

maps compactly the ball

$$B = \{ \mathbf{v} \in C([0,T];X_n) \, | \, \| \mathbf{v}(t) - \mathbf{u}_{0,\delta,n} \|_{X_n} \leq 1 \} \subset C([0,T];X_n)$$

into itself at least for a small enough time T = T(n).

By applying the Schauder fixed point theorem and using the estimate

$$\|\mathcal{M}^{-1}[\varrho(\mathbf{u}^1)] - \mathcal{M}^{-1}[\varrho(\mathbf{u}^2)]\|_{\mathcal{L}(X_n^*,X_n)} \leq C(n,n) \|\varrho(\mathbf{u}^1) - \varrho(\mathbf{u}^2)\|_{L^1(\Omega)},$$

we obtain the existence of at least one solution  $\mathbf{u}_n$  on the interval [0, T(n)].

#### Theorem (Schauder fixed point theorem)

Let  $\mathcal{B}$  be a closed, convex, bounded subset of a Banach space X, and  $\mathcal{T} : \mathcal{B} \to \mathcal{B}$  a compact operator. Then  $\mathcal{T}$  has a fixed point.

Indeed, it is easy to check that

$$\sup_{t\in[0,T]} \|\mathcal{T}[\mathbf{u}]-\mathbf{u}_{0,\delta,n}\|_{X_n} \leq c \sup_{t\in[0,T]} (\|\varrho(t)-\varrho_{0,\delta}\|_{L^1(\Omega)}+t).$$

Then, the continuity in time for  $\varrho(t)$  implies the right-hand side is made small provided T = T(n) is small. We conclude  $\mathcal{T}$  maps  $\mathcal{B}$  into itself over a short time interval.

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